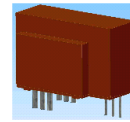


K-No.: 24831

**100 A Current Sensor**

 For the electronic measurement of currents:  
 DC, AC, pulsed, mixed ..., with a galvanic  
 isolation between the primary circuit  
 (high power) and the secondary circuit  
 (electronic circuit)


Date: 18.04.2013

Customer: Standard type

Customers Part no.:

Page 1 of 2

**Description**

- Closed loop (compensation)  
Current Sensor with magnetic field probe
- Printed circuit board mounting
- Casing and materials UL-listed

**Characteristics**

- Excellent accuracy
- Very low offset current
- Very low temperature dependency and offset current drift
- Very low hysteresis of offset current
- Low response time
- Wide frequency bandwidth
- Compact design
- Reduced offset ripple

**Applications**

Mainly used for stationary operation in industrial applications:

- AC variable speed drives and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Switched Mode Power Supplies (SMPS)
- Power Supplies for welding applications
- Uninterruptable Power Supplies (UPS)

**Electrical data – Ratings<sup>1)</sup>**

$I_{PN}$	Primary nominal r.m.s. current	100	A
$R_M$	Measuring resistance $V_C = \pm 12V$	10 ... 200	$\Omega$
	$V_C = \pm 15V$	10 ... 400	$\Omega$
$I_{SN}$	Secondary nominal r.m.s. current	66.7	mA
$K_N$	Turns ratio	1...3 : 1500	

**Accuracy – Dynamic performance data<sup>1)</sup>**

		min.	typ.	max.	Unit
$I_{P,max}$	Max. measuring range				
	@ $V_C = \pm 12V$ , $R_M = 10 \Omega$ ( $t_{max} = 10sec$ )	$\pm 165$			A
	@ $V_C = \pm 15V$ , $R_M = 10 \Omega$ ( $t_{max} = 10sec$ )	$\pm 208$			A
X	Accuracy @ $I_{PN}$ , $T_A = 25^\circ C$		0.1	0.5	%
$\epsilon_L$	Linearity			0.1	%
$I_0$	Offset current @ $I_P = 0$ , $T_A = 25^\circ C$		0.02	0.1	mA
$t_r$	Response time		500		ns
$\Delta t$ ( $I_{P,max}$ )	Delay time at $di/dt = 100 A/\mu s$		200		ns
f	Frequency bandwidth	DC...200			kHz

**General data<sup>1)</sup>**

		min.	typ.	max.	Unit
$T_A$	Ambient operating temperature	-40		+70	$^\circ C$
$T_S$	Ambient storage temperature	-40		+90	$^\circ C$
m	Mass		13,5		g
$V_C$	Supply voltage	$\pm 11.4$	$\pm 12$ or $\pm 15$	$\pm 15.75$	V
$I_C$	Current consumption		18.5		mA
	Constructed and manufactured and tested in accordance with EN 61800-5-1 (Pin 1 - 6 to Pin 7 - 9) Reinforced insulation, Insulation material group 1, Pollution degree 2				
$S_{clear}$	clearance (component without solder pad)	10.2			mm
$S_{creep}$	creepage (component without solder pad)	10.2			mm
$V_{sys}$	System voltage overvoltage category 3			600	V
$V_{work}$	Working voltage (table 7 acc. to EN61800-5-1)			1020	V
$U_{PD}$	Rated discharge voltage		peak value	1400	V
	Max. potential difference acc. to UL 508		RMS	600	$V_{AC}$

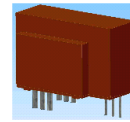
Date	Name	Issue	Amendment
18.04.13	KRe	81	Mechanical outline: marking with UL-sign. and max. potential difference added. CN-662
28.01.08	Le	81	Date changed. Insignificant

Hrsg.: KB-E editor	Bearb.: Le. designer		KB-PM IA: KRe. check		freig.: HS released
-----------------------	-------------------------	--	-------------------------	--	------------------------

K-No.: 24831

**100 A Current Sensor**

For the electronic measurement of currents:  
DC, AC, pulsed, mixed ..., with a galvanic  
isolation between the primary circuit  
(high power) and the secondary circuit  
(electronic circuit)



Date: 18.04.2013

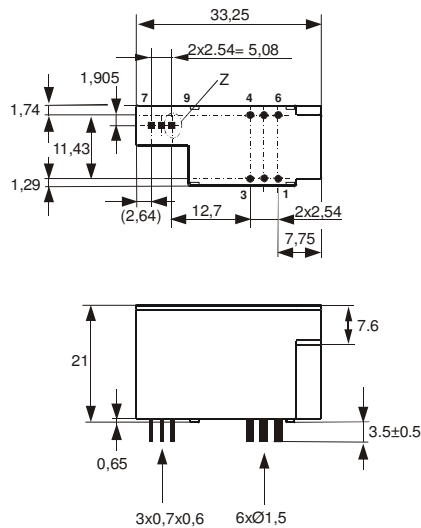
Customer: Standard type

Customers Part no.:

Page 2 of 2

**Mechanical outline (mm):**

General tolerances DIN ISO 2768-c



Tolerances grid distance  
±0,2mm

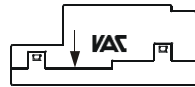
DC = Date Code  
F = Factory

Connections:

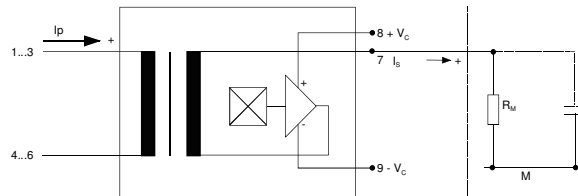
1...6: Ø 1,5 mm  
7...9: 0,6x0,7 mm

Marking:

UL-sign  
4646X413  
F DC



**Schematic diagram**



**Possibilities of wiring for  $V_C = \pm 15V$  (@  $T_A = 70^\circ C$ ,  $R_M = 15 \Omega$ )**

primary windings $N_P$	primary current RMS $I_P [A]$	primary current maximal $\hat{I}_{P,max} [A]$	output current RMS $I_S (I_P) [mA]$	turns ratio $K_N$	primary resistance $R_P [m\Omega]$	wiring
1	100	208	66.7	1:1500	0.12	
2	35	104	46.7	2:1500	0.54	
3	25	69	50	3:1500	1.1	

Temperature of the primary conductor should not exceed 100°C.  
Additional information is obtainable on request.  
This specification is no declaration of warranty acc. BGB §443 dar.

Hrsg.: KB-E  
editor

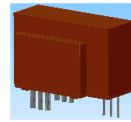
Bearb: Le.  
designer

KB-PM IA: KRe.  
check

freig.: HS  
released

K-No.: 24831

**100 A Current Sensor**

 For electronic current measurement:  
 DC, AC, pulsed, mixed ..., with a galvanic  
 isolation between primary circuit  
 (high power) and secondary circuit


Date: 18.04.2013

Customer:

Customers Part No.:

Page 1 of 3

ME

 A=km  
 1=St  
 2=kg  
 3=g  
 4=l  
 5=m  
 6=m<sup>2</sup>  
 7=m<sup>3</sup>  
 8=mm  
 9:Paar

**Electrical Data (investigate by a type checking)<sup>1)</sup>**

		min.	typ.	max.	Unit
$V_{Ctot}$	Maximum supply voltage (without function) ±15.75 ... ±18 V: for 1s per hour			±18	V
$R_S$	Secondary coil resistance @ $T_A=70^\circ\text{C}$			88	$\Omega$
$R_p$	Primary coil resistance per turn @ $T_A=25^\circ\text{C}$			0.36	m $\Omega$
$X_{Ti}$	Temperature drift of X @ $T_A = -40 \dots +70^\circ\text{C}$			0.1	%
$I_{0ges}$	Offset current (including $I_0, I_{0t}, I_{0T}$ )			0.12	mA
$I_{0t}$	Long term drift Offset current $I_0$		0.04		mA
$I_{0T}$	Offset current temperature drift $I_0$ @ $T_A = -40 \dots +70^\circ\text{C}$		0.04		mA
$I_{0H}$	Hysteresis current @ $I_p=0$ (caused by primary current $3 \times I_{PN}$ )		0.03	0.07	mA
$\Delta I_0/\Delta V_C$	Supply voltage rejection ratio			0.01	mA/V
$i_{loss}$	Offset ripple* (with 1 MHz- filter first order)			0.15	mA
$i_{loss}$	Offset ripple* (with 100 kHz- filter first order)		0.035	0.05	mA
$i_{loss}$	Offset ripple* (with 20 kHz- filter first order)		0.009	0.012	mA
$C_k$	Maximum possible coupling capacity (primary – secondary)		5		pF
	Mechanical Stress according to M3209/3 Settings: 10 – 2000 Hz, 1 min/Oktave, 2 hours An exceptionally high rate of on/off – switching of the supply voltage accelerates the aging process of the sensor.			10g	

**Inspection<sup>1)</sup>** (Measurement after temperature balance of the samples at room temperature)

$K_N(N_1/N_2)$	(V)	M3011/6	Transformation ratio ( $I_p=3*10A, 40-80\text{ Hz}$ )	1...3 : 1500 ± 0.5 %
$I_0$	(V)	M3226	Offset current	< 0.07 mA
$V_{P,eff}$	(V)	M3014	Test voltage, rms, 1s Pin 1 - 6 to Pin 7 - 9	2.5 kV
$V_e$	(AQL 1/S4)		Partial discharge voltage acc. M3024 (RMS) with $V_{vor}$ (RMS)	1500 V 1875 V

**Type Testing** (Pin 1 - 6 to Pin 7 – 9)

Designed according standard EN 61800 with insulation material group 1

$V_W$	HV transient test according (to M3064) (1,2 $\mu\text{s}$ / 50 $\mu\text{s}$ -wave form)			8	kV
$V_d$	Testing voltage acc. M3014 (RMS)		(5 s)	5	kV
$V_e$	Partial discharge voltage acc. M3024 (RMS) with $V_{vor}$ (RMS)			1500 V 1875 V	V

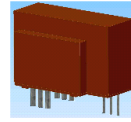
Datum	Name	Index	Änderung
18.04.13	KRe.	81	Applicable document: further standards added. CN-662
28.01.08	Le	81	Page 3: write error in $X_{ges}$ ( $I_{PN}$ ). changed. Insignificant

Hrsg.: KB-E editor	Bearb: Le. designer	KB-PM IA: KRe. check	freig.: HS released
-----------------------	------------------------	-------------------------	------------------------

K-No.: 24831

**100 A Current Sensor**

For electronic current measurement:  
DC, AC, pulsed, mixed ..., with a galvanic  
isolation between primary circuit  
(high power) and secondary circuit



Date: 18.04.2013

Customer:

Customers Part No.:

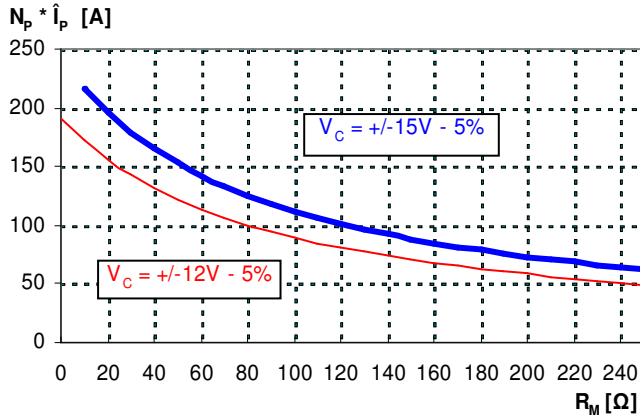
Page 2 of 3

ME

- A=km
- 1=St
- 2=kg
- 3=g
- 4=l
- 5=m
- 6=m<sup>2</sup>
- 7=m<sup>3</sup>
- 8=mm
- 9:Paar

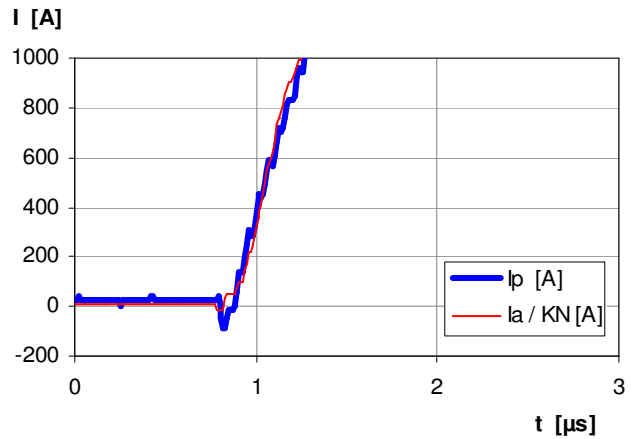
**Limit curve of measurable current  $\hat{i}_p(R_M)$  <sup>1)</sup>**

@ ambient temperature  $T_A \leq 85 \text{ }^\circ\text{C}$



**Maximum measuring range ( $\mu\text{s}$ -range) <sup>1)</sup>**

Output current behaviour of a 3kA current pulse  
@  $V_C = \pm 15\text{V}$  und  $R_M = 25\Omega$



Fast increasing currents (higher than the specified  $I_{p,max}$ ), e.g. in case of a short circuit, can be transmitted because the currents are transformed directly.

The offset ripple can be reduced by an external low pass. Simplest solution is a passive low pass filter of 1st order with

$$f_g = \frac{1}{2\pi \cdot R_M \cdot C_a}$$

In this case the response time is enlarged.

It is calculated from:

$$t'_r \leq t_r + 2,5 R_M C_a$$

**Applicable documents**

Current direction: A positive output current appears at point  $I_s$ , by primary current in direction of the arrow.

Constructed and manufactured and tested in accordance with EN 61800.

Further standards UL 508 ; file E317483, category NMTR2 / NMTR8

Hrsg.: KB-E  
editor

Bearb: Le.  
designer

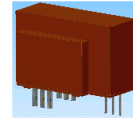
KB-PM IA: KRe.  
check

freig.: HS  
released

K-No.: 24831

**100 A Current Sensor**

For electronic current measurement:  
DC, AC, pulsed, mixed ..., with a galvanic  
isolation between primary circuit  
(high power) and secondary circuit



Date: 18.04.2013

Customer:

Customers Part No.:

Page 3 of 3

ME

A=km  
1=St  
2=kg  
3=g  
4=l  
5=m  
6=m<sup>2</sup>  
7=m<sup>3</sup>  
8=mm  
9:Paar

- $I_{0H}$ : Zero variation of  $I_0$  after overloading with a DC of tenfold the rated value ( $R_M = R_{MN}$ )
- $I_{0t}$ : Long term drift of  $I_0$  after 100 temperature cycles in the range -40 bis 85 °C.
- $t_r$ : Response time (describe the dynamic performance for the specified measurement range), measured as delay time at  $I_P = 0,9 \cdot I_{Pmax}$  between a rectangular current and the output current.
- $\Delta t (I_{Pmax})$ : Delay time (describe the dynamic performance for the rapid current pulse rate e.g short circuit current) measured between  $I_{Pmax}$  and the output current  $i_a$  with a primary current rise of  $di_1/dt = 100 \text{ A}/\mu\text{s}$ .

$X_{ges}(I_{PN})$ : The sum of all possible errors over the temperature range by measuring a current  $I_{PN}$ :

$$X_{ges} = 100 \cdot \left| \frac{I_S(I_{PN})}{K_N \cdot I_{PN}} - 1 \right| \%$$

X: Permissible measurement error in the final inspection at RT, defined by

$$X = 100 \cdot \left| \frac{I_{SB}}{I_{SN}} - 1 \right| \%$$

where  $I_{SB}$  is the output DC value of an input DC current of the same magnitude as the (positive) rated current ( $I_0 = 0$ )

$X_{Ti}$ : Temperature drift of the rated value orientated output term.  $I_{SN}$  (cf. Notes on  $F_i$ ) in a specified temperature range, obtained by:

$$X_{Ti} = 100 \cdot \left| \frac{I_{SB}(T_{A2}) - I_{SB}(T_{A1})}{I_{SN}} \right| \%$$

$\epsilon_L$ : Linearity fault defined by  $\epsilon_L = 100 \cdot \left| \frac{I_P}{I_{PN}} - \frac{I_{Sx}}{I_{SN}} \right| \%$

Where  $I_P$  is any input DC and  $I_{Sx}$  the corresponding output term.  $I_{SN}$ : see notes of  $F_i$  ( $I_0 = 0$ ).

This "Additional information" is no declaration of warranty according BGB §443.

Hrsg.: KB-E  
editor

Bearb: Le.  
designer

KB-PM IA: KRe.  
check

freig.: HS  
released